## PHYS30441 Electrodynamics: Additional Revision Problems - Solutions

1. (a) Start with Gauss' Law  $\nabla \cdot \mathbf{E} = \rho/\epsilon_0$ . Take the time derivative

$$\Rightarrow \nabla \cdot \frac{\partial \mathbf{E}}{\partial t} = \frac{1}{\epsilon_0} \frac{\partial \rho}{\partial t}$$

Substituting from charge conservation

$$\Rightarrow \nabla \cdot \frac{\partial \mathbf{E}}{\partial t} = -\frac{1}{\epsilon_0} \nabla \cdot \mathbf{j}.$$

But Ampere's Law gives

$$\nabla \cdot \mathbf{j} = \frac{1}{\mu_0} \nabla \cdot \nabla \times \mathbf{B} = 0.$$

This leads to a contradiction since  $\nabla \cdot \frac{\partial \mathbf{E}}{\partial t}$  is not always zero.

(b) Taking the divergence of the generalized Ampere's Law:

$$\nabla \cdot (\nabla \times \mathbf{B}) = \mu_0 \nabla \cdot \left( \mathbf{j} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

The identity  $\nabla \cdot (\nabla \times \mathbf{B}) = 0$  and Gauss' Law  $\nabla \cdot \mathbf{E} = \rho/\epsilon_0$  allows the above to be written as

$$0 = \nabla \cdot \mathbf{j} + \frac{\partial \rho}{\partial t}.$$

This is the continuity of charge.

2. Energy density

$$\frac{1}{2}\epsilon_0 E^2 \simeq 440 \text{ Jm}^{-3}.$$

3. Field

$$B \simeq \frac{\mu_0 NI}{L} \simeq \frac{4\pi \times 10^{-7} \times 1100 \times 7700}{5.3} \simeq 2.0 \text{ T}.$$

Stored energy

$$U_m = \frac{1}{2\mu_0} \int_V B^2 dV \simeq \frac{1}{2\mu_0} B^2 \times \pi r^2 L \simeq \frac{1}{2 \times 4\pi \times 10^{-7}} \times 2^2 \times \pi \times (1.25)^2 \times 5.3 \simeq 4.1 \times 10^7 \text{ J.}$$

4. Consider the vector identity  $\nabla \times (\nabla V) = 0$ . The converse also holds: if  $\nabla \times \mathbf{v} = 0$ , we can find V such that  $\mathbf{v} = \nabla V$ . Similarly, considering the vector identity  $\nabla \cdot (\nabla \times \mathbf{A}) = 0$ , the converse also holds: if  $\nabla \cdot \mathbf{B} = 0$ , we can find  $\mathbf{A}$  such that  $\mathbf{B} = \nabla \times \mathbf{A}$ . (Note that the latter works for static and for time-varying fields  $\mathbf{B}$ .)

From Faraday's Law

$$\nabla \times \mathbf{E} = -\frac{\partial}{\partial t} (\nabla \times \mathbf{A}) \implies \nabla \times \left( \mathbf{E} + \frac{\partial \mathbf{A}}{\partial t} \right) = 0.$$

Hence we can write

$$\mathbf{E} + \frac{\partial A}{\partial t} = -\nabla V.$$

Thus we can represent the EM fields as

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t}, \qquad \mathbf{B} = \nabla \times \mathbf{A}.$$

5. Starting with  $\nabla \times \nabla \times \mathbf{E} = -\frac{\partial}{\partial t} \nabla \times \mathbf{B}$  and using

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \epsilon_0 \mu_0 \frac{\partial \mathbf{E}}{\partial t} \text{ with } \mathbf{j} = \mathbf{0} \text{ and } \epsilon_0 \mu_0 = \frac{1}{c^2}$$
$$\Rightarrow \nabla \times \nabla \times \mathbf{E} = -\frac{\partial}{\partial t} \left( \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} \right).$$

The standard vector identity allows the left-hand side to be expanded:

$$\nabla \times \nabla \times \mathbf{E} = \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 (E) = -\nabla^2 (E)$$

where Gauss' Law for a region free of sources has been applied, hence  $\nabla \cdot \mathbf{E} = 0$ .

Thus we have:

$$\nabla^2 \mathbf{E} - \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} = 0.$$

A similar approach taking the curl of the generalised Ampere's equation should be followed to also obtain

$$\nabla^2 \mathbf{B} - \frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2} = 0.$$

6. If **A** is a vector potential for **B**, then  $\nabla \times \mathbf{A} = \mathbf{B}$ . Hence

$$\nabla \times (\mathbf{A} + \nabla g) = \nabla \times \mathbf{A} + \nabla \times \nabla g = \nabla \times \mathbf{A} = \mathbf{B}.$$

(since  $\nabla \times \nabla g = 0$ ; a vector identity). Thus  $\mathbf{A} + \nabla g$  is also a vector potential for  $\mathbf{B}$ . Similarly, using

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t},$$

we obtain

$$-\nabla\left(V - \frac{\partial g}{\partial t}\right) - \frac{\partial}{\partial t}(\mathbf{A} + \nabla g) = -\nabla V + \nabla\frac{\partial g}{\partial t} - \frac{\partial}{\partial t}\nabla g - \frac{\partial \mathbf{A}}{\partial t}$$
$$= -\nabla V - \frac{\partial \mathbf{A}}{\partial t} = \mathbf{E}.$$

So,

$$\mathbf{A} \to \mathbf{A} + \nabla g, V \to V - \frac{\partial g}{\partial t}$$

are also valid potentials for  $\mathbf{E}$ .

7. The Lorenz gauge condition is

$$\frac{1}{c^2}\frac{\partial V}{\partial t} + \nabla \cdot \mathbf{A} = 0,$$

where

$$\frac{1}{c^2} = \mu_o \epsilon_0.$$

Hence

$$\frac{\partial V}{\partial t} = -c^2 B_0 \nabla \cdot \left[ \frac{yz}{a} \sin \omega t \hat{\mathbf{y}} + \left( \frac{x^3}{a^2} + 2z \right) \cos \omega t \hat{\mathbf{z}} \right] = -c^2 B_0 \left( \frac{z}{a} \sin \omega t + 2 \cos \omega t \right).$$
  
Integrating w.r.t.  $t \Rightarrow V = c^2 \frac{B_0}{\omega} \left( \frac{z}{a} \cos \omega t - 2 \sin \omega t \right) + V_0(x, y, z).$ 

Note that the 'constant of integration' is an arbitrary function of space (x, y, z) so the scalar potential V is NOT unique. We can add any spatial function, but the obvious (and simplest) choice is  $V_0 = 0$ . Proceeding with this,

$$B = \nabla \times \mathbf{A}$$

$$= B_0 \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ 0 & \frac{yz}{a} \sin \omega t & \left(\frac{x^3}{a^2} + 2z\right) \cos \omega t \end{vmatrix}$$

$$= B_0 \left( -\hat{\mathbf{x}} \frac{y}{a} \sin \omega t - \hat{\mathbf{y}} \frac{3x^2}{a^2} \cos \omega t \right).$$

(This is unique, for the given vector potential). Also,

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t}$$
  
=  $-\frac{c^2 B_0}{a\omega} \cos \omega t \hat{\mathbf{z}} - B_0 \frac{yz}{a} \omega \cos \omega t \hat{\mathbf{y}} + B_0 \left(\frac{x^3}{a^2} + 2z\right) \omega \sin \omega t \hat{\mathbf{z}}$   
=  $B_0 \left[ -\frac{c^2}{a\omega} \cos \omega t \hat{\mathbf{z}} - \frac{\omega}{a} yz \cos \omega t \hat{\mathbf{y}} + \left(\frac{x^3}{a^2} + 2z\right) \omega \sin \omega t \hat{\mathbf{z}} \right]$ 

(You may obtain a different answer if you chose a different V — differing by  $\nabla V_0$ ).

$$Q8(b)$$

$$\nabla. (\nabla \times A) = \frac{\partial}{\partial x} \left( \frac{\partial A}{\partial y} - \frac{\partial A}{\partial z} \right) + \frac{\partial}{\partial y} \left( \frac{\partial A}{\partial z} - \frac{\partial A}{\partial x} \right)$$

$$+ \frac{\partial}{\partial z} \left( \frac{\partial A}{\partial x} - \frac{\partial A}{\partial y} \right) = 0,$$
Since  $\frac{\partial}{\partial x} \left( \frac{\partial A}{\partial y} \right) = \frac{\partial}{\partial y} \left( \frac{\partial A}{\partial z} \right), \text{ et } c$ 
Index notation

$$\nabla \cdot \left( \nabla_{\mathbf{x}} \mathbf{A} \right) = \frac{\partial}{\partial \mathbf{x}_{i}} \left( \varepsilon_{ijk} \frac{\partial \mathbf{A}_{k}}{\partial \mathbf{x}_{j}} \right) = \varepsilon_{ijk} \frac{\partial}{\partial \mathbf{x}_{i}} \left( \frac{\partial \mathbf{A}_{k}}{\partial \mathbf{x}_{j}} \right) = 0.$$

Since with respect to interchange ica) Eijk antisymmetric

 $\frac{\partial}{\partial x_i} \left( \frac{\partial A_k}{\partial x_i} \right)$  symmetric.

Q8 (c)  
Let's consider the 
$$\hat{x}$$
 component of  $\nabla(fg)$ .  
 $\left[\nabla(fg)\right]_{x} = \frac{\partial}{\partial x}(fg) = f(\frac{\partial g}{\partial x}) + g(\frac{\partial f}{\partial x})$   
 $= f\left[\nabla g\right]_{x} + g\left[\nabla f\right]_{x}$   
Same results hold for the  $\hat{y}$  and  $\hat{z}$   
components  
 $\cdot \cdot \cdot \nabla(fg) = f(\nabla g) + g(\nabla f)$   
In index notation:  
 $\nabla(fg) = \hat{x}_{i}\frac{\partial}{\partial x_{i}}(fg) = f(\hat{x}_{i}\frac{\partial g}{\partial x_{i}}) + g(\hat{x}_{i}\frac{\partial f}{\partial x_{i}})$   
 $= f(\nabla g) + g(\nabla f)$ 

Q8(d)  $\nabla \cdot (fA) = \frac{\partial}{\partial x} (fA_x) + \frac{\partial}{\partial y} (fA_y) + \frac{\partial}{\partial z} (fA_z)$  $= \int \left( \frac{\partial A_{x}}{\partial x} + \frac{\partial A_{y}}{\partial y} + \frac{\partial A_{z}}{\partial z} \right) + \left( A_{x} \frac{\partial f}{\partial x} + A_{y} \frac{\partial f}{\partial y} + A_{z} \frac{\partial f}{\partial z} \right)$  $= f(\nabla \cdot \underline{A}) + \underline{A} \cdot (\nabla f)$ 

In index notation  $\nabla \cdot (fA) = \frac{\partial}{\partial x_i} (fA_i) = f(\frac{\partial A_i}{\partial x_i}) + A_i(\frac{\partial f}{\partial x_i})$  $= f(\nabla . A) + A.(\nabla f)$ 

$$Q = (b)$$
From  $E_{\mu} = V m_{\mu}c^{2}$  and answer to part(a)  

$$V = \frac{m_{\pi}^{2} + m_{\mu}^{2}}{2m_{\mu}m_{\pi}}$$
From  $V^{2} = (1 - \beta^{2})^{-1}$   
 $\beta^{2} = 1 - V^{2} = 1 - \frac{4m_{\mu}m_{\pi}}{(m_{\pi}^{2} + m_{\mu}^{2})^{2}}$   
 $= \frac{(m_{\pi}^{2} + m_{\mu}^{2})^{2} - 4m_{\mu}m_{\pi}}{(m_{\pi}^{2} + m_{\mu}^{2})^{2}}$   
 $= \frac{(m_{\pi}^{2} - m_{\mu}^{2})^{2}}{(m_{\pi}^{2} + m_{\mu}^{2})^{2}}$   
 $= \frac{(m_{\pi}^{2} - m_{\mu}^{2})^{2}}{(m_{\pi}^{2} + m_{\mu}^{2})^{2}}$ 
(speed in with of c)

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N.B. In the question you are asked for the (vector) E. A complete answer therefore requires the direction as well as the magnitude I

$$\begin{split} \mathfrak{Q} \mathfrak{M}(c) & \underbrace{\mathsf{Within beam}}_{\mathsf{S} < \mathsf{a}} & \underbrace{\mathsf{Outside beam}}_{\mathsf{S} > \mathsf{a}} \\ & \underbrace{\mathsf{E}} = \frac{\mathsf{s}}{2\mathfrak{e}_{\mathsf{o}}} \overset{\circ}{\mathsf{s}} = -\nabla \mathsf{V} = -\frac{\mathsf{d}}{2\mathfrak{e}_{\mathsf{s}}} \overset{\circ}{\mathsf{s}} \\ & \underbrace{\mathsf{E}} = \frac{\mathsf{a}}{2\mathfrak{e}_{\mathsf{o}}} \overset{\circ}{\mathsf{s}} \\ & \underbrace{\mathsf{V}} = -\frac{\mathsf{a}}{2\mathfrak{e}_{\mathsf{o}}} \ln \mathsf{s} + \mathsf{K} \\ & \underbrace{\mathsf{V}} = -\frac{\mathsf{a}}{2\mathfrak{e}_{\mathsf{o}}} \ln \mathsf{s} + \mathsf{K} \\ & \underbrace{\mathsf{Ensuring continuity at s}}_{\mathsf{chossing V} = \mathsf{o}} \mathsf{at s} = \mathsf{o} \\ & \underbrace{\mathsf{V}} = -\frac{\mathsf{a}}{2\mathfrak{e}_{\mathsf{o}}} \left[ \mathsf{Ins} + \mathsf{K} \\ & \underbrace{\mathsf{Ensuring continuity at s}}_{\mathsf{chossing V} = \mathsf{o}} \mathsf{at s} = \mathsf{o} \\ & \underbrace{\mathsf{V}} = -\frac{\mathsf{a}}{2\mathfrak{e}_{\mathsf{o}}} \left[ \mathsf{Ins} + \mathsf{L} \\ & \underbrace{\mathsf{Ensuring continuity at s}}_{\mathsf{chossing V} = \mathsf{o}} \mathsf{at s} = \mathsf{o} \\ & \underbrace{\mathsf{M}} = -\frac{\mathsf{d}}{2\mathfrak{e}_{\mathsf{o}}} \left[ \mathsf{Ising definition f}_{\mathsf{curl in}} \mathsf{out in} \\ & \underbrace{\mathsf{chossing P}}_{\mathsf{curl in}} \mathsf{as is I} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \overset{\circ}{\mathfrak{s}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \overset{\circ}{\mathfrak{s}} \\ & \underbrace{\mathsf{R}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \overset{\circ}{\mathfrak{s}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \overset{\circ}{\mathfrak{s}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{Chossing A = 0 at s} : \mathsf{o}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{A}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{R}} = \frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{R}} = \frac{\mathsf{L}}{\mathfrak{P}} \overset{\circ}{\mathfrak{P}} \\ & \underbrace{\mathsf{R}} = \frac{\mathsf{L}}{\mathfrak{P}} \overset{\circ}{\mathfrak{P}} \\ & \underbrace{\mathsf{R}} = -\frac{\mathsf{M} \cdot \mathsf{e}}{\mathfrak{P} \mathsf{T}} \\ & \underbrace{\mathsf{R}} = -\frac{\mathsf{M} \cdot \mathsf{R}} \\ & \underbrace{\mathsf{R}} = -\frac{\mathsf{R} \cdot \mathsf{R}} \\ & \underbrace{\mathsf{R}} = -\frac{\mathsf$$





(f) BO JUXB JUXB JOTCES are in opposit forces are in opposite directions · F= e (E+ UxB) is radial - Within beam Outside beam  $F = e\left(\frac{5P}{2\varepsilon_0} - \frac{5^2 \mu_0 P 5}{2}\right) \quad F = e\left(\frac{aP}{2\varepsilon_0} - \frac{5^2 \mu_0 a P}{25}\right)$  $= \underline{esp}\left(\frac{1}{\varepsilon_0} - \underline{v}^2 \mu_0\right) = \underline{eap}\left(\frac{1}{\varepsilon_0} - \underline{v}^2 \mu_0\right)$ In both cases it is tempting to surmise that  $F \Rightarrow 0$  as  $v^2 \Rightarrow \bot = c^2$  $E_0 \mu_0$ lowever, we shall return to this problem after we have, derived the relativistic equations for P, j, V, A, E, Betc.





 $E = -\frac{\partial V}{\partial S} = -\frac{\lambda}{2\pi\epsilon_o} \left[ \frac{S(L^2 + S^2)^{-1/2}}{(L^2 + S^2)^{1/2} + L} - \frac{1}{S} \right]$ As  $L \to \infty$   $E \to \frac{\lambda}{2\pi\epsilon_o S}$  (Field is radially <u>ontwards</u>) This is consistent with the (outside beam) result in Q10(a) when  $\lambda = \pi\epsilon_a^2 p$ .

Alternative approach to definite integral in QII.) (a)

$$V = \frac{\lambda}{4\pi\epsilon_{o}} \left[ \ln \left\{ (s^{2} + 2^{2})^{1/2} + 2 \right\} \right]^{L}$$
  
=  $\frac{\lambda}{4\pi\epsilon_{o}} \left[ \ln \left\{ (s^{2} + L^{2})^{1/2} + L \right\} - \ln \left\{ (s^{2} + L^{2})^{1/2} - L \right\} \right]$   
=  $\frac{\lambda}{4\pi\epsilon_{o}} \left[ \ln \left\{ (s^{2} + L^{2})^{1/2} + L \right\} - \ln \left\{ (s^{2} + L^{2})^{1/2} - L \right\} \right]$ 

$$= \frac{\lambda}{4\pi\epsilon_{0}} \ln \left\{ \frac{(s^{2} + L^{2})'_{2} + L}{(s^{2} + L^{2})'_{2} - L} \right\}$$

$$= \frac{\lambda}{4\pi\epsilon_{0}} \ln \left\{ \frac{[(s^{2} + L^{2})'_{2} + L]^{2}}{(s^{2} + L^{2}) - L^{2}} \right\}$$

$$= \frac{\lambda}{4\pi\epsilon_{0}} 2 \left[ \ln \left\{ \frac{(s^{2} + L^{2})'_{2} + L}{(s^{2} + L^{2}) - L^{2}} \right\}$$

$$= \frac{\lambda}{4\pi\epsilon_{0}} \left[ \ln \left\{ \frac{(s^{2} + L^{2})'_{2} + L}{(s^{2} + L^{2})'_{2} + L} \right\} \right]$$

multiply top and bottom by  $(s^2+L^2)^{1/2}+L$ 

which is equivalent to the result obtained using  $2 \begin{bmatrix} J_0^L \end{bmatrix}_0^L$ .

QII (b) Since  $I = I\hat{z}$  has only one component the solution for  $A = A\hat{z}$  is using similar to that for V in part (a).

$$A = 2 \mu_0 I \int_{0}^{L} \frac{dz}{(s^2 + z^2)^{1/2}}$$

$$= \frac{\gamma_{0}T}{2\pi} \left[ \ln \left\{ \left( L^{2} + s^{2} \right)^{1/2} + L \right\} - \ln s \right]$$

Since  $A_z$  is the only non-zero component and it varies only as a function of s then in the expression for  $\nabla \times A$  in cylindrical coordinates  $B = -\frac{\partial A_z}{\partial s} = -\frac{\gamma_0 T}{2\pi} \left[ \frac{1}{(L^2 + s^2)^2 + L} - \frac{1}{s} \right] \hat{Q}$ 

This is consistent with the (outside beam) result in QIO(b) when  $I = \tau \tau a^2 \rho \tau$ .

Quedian 12)  
In all three cases the monopole term is  

$$V_{o}(c) = \frac{1}{4\pi\epsilon_{o}} \frac{1}{r} (3q-q) = \frac{1}{4\pi\epsilon_{o}} \frac{2q}{r}$$
(i) The dipole moment  $P = \int c' \rho(c') dc'$   
(a)  $P = 3q \alpha \hat{z}$   
(b)  $P = (-q)(-\alpha)\hat{z} = q\alpha\hat{z}$   
(c)  $P = 3q\alpha\hat{y}$   

$$V_{dipole} = \frac{\hat{c} \cdot P}{4\pi\epsilon_{o}r^{2}} \qquad \hat{c} = \sin\theta\cos\beta\hat{z} + \sin\theta\sin\beta\hat{y}$$
(ii) (a)  $V(r,\theta) = \frac{1}{4\pi\epsilon_{o}} \begin{bmatrix} 2q + 3q\alpha\cos\theta + \dots \\ r^{2} \end{bmatrix}$   
(b)  $V(r,\theta) = \frac{1}{4\pi\epsilon_{o}} \begin{bmatrix} 2q + \frac{3q\alpha\cos\theta}{r^{2}} + \dots \\ r^{2} \end{bmatrix}$   
(b)  $V(r,\theta) = \frac{1}{4\pi\epsilon_{o}} \begin{bmatrix} 2q + \frac{3q\alpha\cos\theta}{r^{2}} + \dots \\ r^{2} \end{bmatrix}$ 

Q13)  
(a) We want to keep the same charge distribution  

$$P(E')$$
, but we want its location with respect  
to the origin to be  $\Gamma' - \alpha$ .  
 $P \rightarrow P' = \int (\Gamma' - \alpha) P(E') dr'$   
 $= \int \Gamma' P(E') dr' - \alpha \int P(E') dr'$   
can be taken outside  
the integral because it  
is a constant.  
 $= P - \alpha \alpha$ , where  $\alpha$  is the total charge.  
 $P$  is unchanged by a displacement if the  
total charge is zero.

QIB)  
(b) (ii) For the dipole in part (i):  

$$P = p\hat{z} = p(\cos \theta \hat{r} - \sin \theta \hat{\theta})$$

$$\int_{\theta} \hat{r} \hat{r} \hat{\theta}$$

$$\int_{\theta} \hat{r} \hat{r} \hat{r} \hat{\theta} = [p\cos \theta]\hat{r}$$

$$\frac{1}{4\pi\epsilon_{0}r^{3}} \left(3[p,\hat{r}]\hat{r} - p\right) = \frac{1}{4\pi\epsilon_{0}r^{3}} \left(3p\cos \theta \hat{r} - p[\cos \theta \hat{r} - \sin \theta \hat{\theta}]\right)$$

$$= \frac{p}{4\pi\epsilon_{0}r^{3}} \left(2\cos \theta \hat{r} + \sin \theta \hat{\theta}\right),$$

which is consistent with the result in part(i).

Q|3)(b) (iii)  $E = -\nabla V = -1 \nabla (\hat{r}, \hat{p})$ Using vector identity(3) (Eq. 1.1)  $\nabla\left(\frac{\hat{r} \cdot P}{r^2}\right) = \left(\frac{\hat{r} \cdot P}{r^2}\right) \nabla\left(\frac{1}{r^2}\right) + \frac{1}{r^2} \nabla\left(\hat{r} \cdot P\right)$  $= (\hat{\underline{r}} \cdot \underline{p})\nabla(\frac{1}{r^2}) + \frac{1}{r^2}\left[\hat{\underline{r}} \times (\nabla \times \underline{p}) + \underline{p} \times (\nabla \times \hat{\underline{r}}) + (\hat{\underline{r}} \cdot \nabla)\hat{\underline{p}} + (\underline{p} \cdot \nabla)\hat{\underline{r}}\right]$ (Eqn 1.2) [using vector identity (4)] This looks horendous, but bear with me! P=pp where p is a constant scalar and p is a constant vector. . . Txp and (E.V.) p are trivially zero. Also since Î is a radial vector Vx î must be zero, but let's show this for one component explicitly:  $\left[\nabla_{x}\hat{r}\right]_{x} = \left[\nabla_{x}\left(\frac{r}{r}\right)\right]_{x} = \frac{\partial}{\partial y}\left(\frac{z}{r}\right) - \frac{\partial}{\partial z}\left(\frac{y}{r}\right) = z\left(-\frac{1}{2}\frac{2y}{r^{3}}\right) - y\left(-\frac{1}{2}\frac{2z}{r^{3}}\right)$ 

Thus Equation (1.2) becomes  

$$\nabla\left(\frac{\hat{\Gamma} \cdot p}{r^{2}}\right) = \left(\hat{\Gamma} \cdot p\right) \nabla\left(\frac{1}{r^{2}}\right) + \frac{1}{r^{2}}\left(\underline{P} \cdot \nabla\right) \hat{\Gamma} \quad (Eqn 1.3)$$
Writing out explicitly in contential coordinates:  

$$\nabla\left(\frac{1}{r^{2}}\right) = \left(\hat{x}\frac{\partial}{\partial x} + \hat{y}\frac{\partial}{\partial y} + 2\frac{\partial}{\partial z}\right) \left[x^{2} + y^{2} + 2^{x}\right]^{1}$$

$$= -2\left(x\hat{x}\hat{x} + y\hat{y}\hat{y} + 2\hat{z}\hat{z}\right) = -2\hat{\Gamma} = -2\hat{\Gamma} \left(\frac{Eqn}{r^{3}}\right)^{1/2}$$

$$(P \cdot \nabla)\hat{\Gamma} = \left(P \cdot \nabla\right) \left(\frac{\Gamma}{r}\right) = \left(P_{x}\frac{\partial}{\partial x} + P_{y}\frac{\partial}{\partial y} + P_{z}\frac{\partial}{\partial z}\right) \left(x\hat{x} + y\hat{y}\hat{y} + 2\hat{z}\hat{z}\right) \left[x^{2} + y^{2} + 2^{x}\right]^{1/2}$$

$$= \left(\frac{P_{x}\hat{x} + P_{y}\hat{y} + P_{z}\hat{z}}{\left[x^{2} + y^{2} + 2^{x}\right]^{1/2}} - \frac{1}{2} \cdot 2\left(\frac{P_{x}x + P_{y}y + P_{z}z}{\left[x^{2} + y^{2} + 2^{x}\right]^{1/2}}\right)^{1/2}$$

$$= \frac{P}{r} - \left(\frac{\Gamma \cdot P}{r^{3}}\right)\Gamma \qquad (Eqn 1.5)$$
Substituting Eqns (1.4) and (1.5) into Eqn (1.3) gives  

$$\nabla\left(\frac{\hat{\Gamma} \cdot P}{r^{2}}\right) = -\frac{2}{r^{3}}\left(\hat{\Gamma} \cdot P\right)\hat{\Gamma} + \frac{1}{r^{2}}\left[\frac{P}{r} - \left(\frac{\Gamma \cdot P}{r^{3}}\right)\Gamma\right]$$

$$= -\frac{3}{r^{3}}\left(\hat{\Gamma} \cdot P\right)\hat{\Gamma} + \frac{P}{r^{3}}$$
Substituting into Eqn (1.1) yields the desired result:  

$$\frac{F}{r} = dipde = \frac{1}{A\tau\tau \xi, r^{3}}\left(3\Gamma(P, \hat{\Gamma})\hat{\Gamma} - P\right)$$

Notes:

An alternative treatment of  $V(\frac{1}{r^2})$  using vector identity (3)  $\nabla\left(\frac{1}{r^2}\right) = 2\left(\frac{1}{r}\right)\nabla\left(\frac{1}{r}\right) = \frac{2}{r}\left(-\frac{\hat{r}}{r^2}\right) = -\frac{2\tilde{r}}{r^3}$ avoids having to write out cartesian coordinates

Q14 (a) Stoke's Theorem appled to v = Ø =  $\int (\nabla \times [\infty \in ]) da = \oint \beta \in . dl = \subseteq . \oint \beta dl (A)$ (since c is a constant) From vector identity (7) (B)  $\nabla \times [\phi c] = \phi (\nabla \times c) - c \times [\nabla \phi]$ = o since s is a constant Substituting (B) into (A)  $c \cdot \int \phi \, dl = -\int (c \times [\nabla \phi]) \, da = -c \cdot \int [\nabla \phi] \times da$ from vector identity (1) Since q is an arbitrary constant vector it must be the case that - [[vø] x da = fødl (c) c as required.

Let 
$$\phi = \hat{\Gamma} \cdot \hat{\Gamma}'$$
  
and re-write eqn. (c) with primed roordinates  
used for differentials  

$$\int_{c} (\hat{\Gamma} \cdot \hat{\Gamma}') dt' = -\int_{c} [\nabla_{r} \cdot (\hat{\Gamma} \cdot \hat{\Gamma}')] \times da$$

$$= \int_{c} \hat{\Gamma} \times da = \hat{\Gamma} \times a \quad \text{as required}$$

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Q14) (b)  $\underline{M} = \underline{m}\hat{Z} = \underline{m}(\cos\theta\hat{r} - \sin\theta\hat{\theta})$ Substituting into the expression given in the question:  $. \quad \underline{B}_{dipole} = \underline{\mu}_{0} = \frac{3}{4\pi\epsilon^{3}} [3m\cos\theta\hat{r} - m(\cos\theta\hat{r} - \sin\theta\hat{\theta})]$ 

$$= \frac{\mu_{om}}{4\pi r^{3}} \left[ 2\cos\theta \hat{r} + \sin\theta \hat{\theta} \right],$$

which is the expression we obtained in Lecture 7.